

# **ODX-6000**

### **6000VA DC/AC INVERTER**

#### **GENERAL FEATURES:**

Sine wave output voltage
Suitable for motors control
Adjustable output frequency
Adjustable output voltage
High input-output isolation 3000Vrms
Remote off opto-coupled
Alarm by isolated relay contacts
Configurable input: Reverse or Mid power

Remote control via RS232

CAN BUS (optional)

Parallelable output (optional)

Railway version EN50155 (optional) Fire and smoke: EN45545-2 approved















	24Vdc	48Vdc	72Vdc	110Vdc
	16.8 30V	33.6 60V	50.4 90V	77 138V
400Vac	<b>ODX-6000-7502</b>	<b>ODX-6000-7505</b>	<b>ODX-6000-7506</b>	<b>ODX-6000-7507</b>
	3500 W	6000 W	6000 W	6000 W



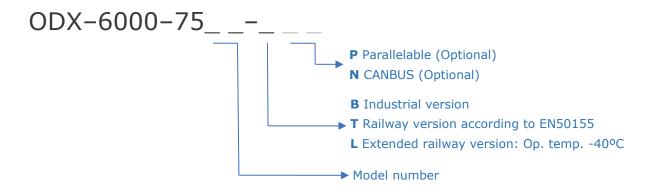
INPUT							
Input voltage range	-30, +25% Vin nom						
Maximum input ripple	5% Vin nom (Vrms, 100Hz)						
ОИТРИТ							
Nominal output voltage (Von)	See table						
Output voltage range	20100% of Von (adjust via remote control)						
Output frequency	50 / 60Hz via DIP-switch, 575Hz via RS-232						
Load regulation	< 4.5%						
Line regulation	< 2% Vin -25% +25% < 10% Vin -30% +30% < 20 % Vin -40 % +40 % (10	0ms)					
Output wave distortion THD	< 2% (average of 16 samples)						
Output HF ripple	< 2.5%						
ENVIRONMENTAL	Options B and T	Option L (Note-1)					
Storage temperature	-25 80 °C	-40 80 °C					
Operating temperature: Full load Operating temperature: 62.5 % load	-25 55 °C (EN50155 OT1) -25 70 °C (EN50155 OT3) -25 85 °C (EN50155 OT5)	-40 55 °C (EN50155 OT2) -40 70 °C (EN50155 OT4) -40 85 °C (EN50155 OT6)					
Operating temperature: 25 % load	5 95%	-40 63 °C (LN30133 010)					
Relative humidity without condensation  Maximum altitude		% of load					
	2000m at full load, 2500m at 95 Internal controlled internal fan	% OI 10au					
Cooling  Shock and Vibrations assorting to		R hady maunted					
Shock and Vibrations according to MTBF (MIL-HDBK-217-E; Gb, 25°C)	EN61373:2011 Category 1 Class 100.000 h	B body modified					
EMC	100.000 11						
	ENG1000 C 2 ENE0121 2 2						
Immunity according	EN61000-6-2, EN50121-3-2						
Emissions according	EN61000-6-4, EN50121-3-2						
SAFETY	20001/ / 5011 / 4						
Dielectric strength: Input /output	3000Vrms / 50Hz / 1min						
Dielectric strength: Output / Earth	1500Vrms / 50Hz / 1min						
Dielectric strength: Input / Earth	500Vrms / 50Hz / 1min						
Safety according to	EN60950-1, EN62368-1	ntions T and L. uniburat varians)					
Fire and smoke	EIN45545-2 approved (only for o	ptions <b>T</b> and <b>L</b> , railway versions)					
MECHANICAL	0050						
Weight	< 8950 g						
Protection degree	IP20						
PROTECTIONS							
Against overloads	Current and I <sup>2</sup> T limited (see ove	rload protection curve)					
Against over-temperature	Shutdown with auto-recovery						
CONTROL							
Output OK LED	Green						
Input OK LED	Green						
Alarm LED	Red						
Input alarm	Open when alarm. Maximum rati						
Output alarm	Open when alarm. Maximum rati						
Remote OFF input	Off applying 15143 Vdc (acc. to	· · ·					
Configurable input (reverse or mid-power)	ON: applying 15143 Vdc (acc.	to EN50155), Impedance $>$ 35k $\Omega$					

Note-1: Is not recommended to handle connectors below -25°C



#### **ORDERING CODES**

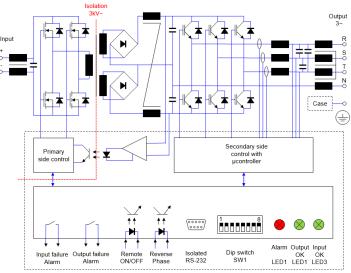
Model	Input voltage DC [V]	Input voltage range [V]	Max. Input current [A]	Output voltage AC [V]	Output current [A]	Active output power [W]	Appar. output power [VA]	Output pea 5s (rms) [A]	(lopk) 10ms [A]	Efficien.	No load input current [A]
ODX-6000-7502	24	16.8 - 30	232	400	6.50	3500	4500	7.8A	20	91.0	1.70
ODX-6000-7505	48	33.6 - 60	191	400	8.66	6000	6000	11.5	20	93.6	0.85
ODX-6000-7506	72	50.4 - 90	127	400	8.66	6000	6000	11.5	20	94.3	0.58
ODX-6000-7507	110	77 - 138	83	400	8.66	6000	6000	11.5	20	94.2	0.38



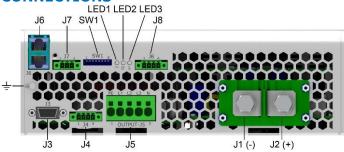
Accessories must be ordered in a separate order line The option P (parallelable) always has N (CANBUS) Please check availability for P or N options



#### **BLOCKS DIAGRAM**

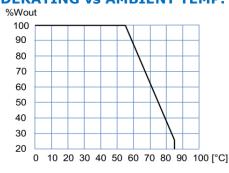


#### CONNECTIONS



J1	-Vin	Terminal M8					
J2	+Vin	Terrilliai Pio					
J5 - 1	Protective Earth						
J5 - 2	+Vin Protective Earth Output R Output S Output T Output Neutral + Configurable input - Configurable input - Remote - Remote Output alarm Input alarm CAN L (optional Can bus CAN H (optional Can bus SND CAN RS-232 Rx RS-232 Tx RS-232 GND Not connected						
J5 - 3	Output S	Cables 2.5 4mm <sup>2</sup>					
J5 - 4	+Vin Protective Earth Output R Output S Output S Output T Output Neutral + Configurable input - Configurable input + Remote - Remote Output alarm Input alarm CAN L (optional Can bus) GND CAN RS-232 RX RS-232 TX RS-232 GND Not connected Optional Parallel operation Master / Slave Parallel / Stand alone Local / Remote						
J5 - 5	Output Neutral						
J4 - 1	+ Configurable input						
J4 - 2	+Vin Protective Earth Output R Output S Output S Output T Output Neutral + Configurable input - Configurable input + Remote - Remote Output alarm Input alarm CAN L (optional Can bus) GND CAN RS-232 RX RS-232 TX RS-232 GND Not connected Optional Parallel operation Master / Slave Parallel / Stand alone Local / Remote	Dhaaniy Cantast MC1 F/4 CF 2 91					
J4 - 3	+ Remote	Phoenix Contact MC1.5/4-GF-3.81 Recommended female:					
J4 - 4	- Remote	Phoenix Contact MC1.5/4-STF-3.81					
J8 - 1, 2	Output alarm	Filoenix Contact MC1.5/4-511-5.61					
J8 - 3, 4	Input alarm						
J7 - 1	CAN L (optional Can bus)	Phoenix Contact MC1.5/3-GF-3.81					
J7 - 2	2 +Vin - 1 Protective Earth - 2 Output R - 3 Output S - 4 Output T - 5 Output Neutral - 1 + Configurable input - 2 - Configurable input - 3 + Remote - 4 - Remote - 4 - Remote - 1, 2 Output alarm - 1 CAN L (optional Can bus) - 2 CAN H (optional Can bus) - 3 GND CAN - 2 RS-232 Rx - 3 RS-232 Rx - 5 RS-232 GND rest Not connected - J6B Optional Parallel operation 1 - 1 Master / Slave 1 - 2 Parallel / Stand alone 1 - 6 Local / Remote 1 - 7 50Hz / 60Hz	Recommended female:					
J7 - 3	GND CAN	Phoenix Contac MC1.5/3-STF-3.81					
J3 - 2	RS-232 Rx						
J3 - 3	RS-232 Tx	Female D-Sub DB9					
J3 - 5	RS-232 GND	Terriale D-300 DD3					
J3 rest	J4 - 3						
J6A - J6B	Optional Parallel operation	RJ45					
SW1 - 1	Master / Slave	ON (down): Slave					
SW1 - 2	Parallel / Stand alone	ON (down): Stand alone					
SW1 - 6	Local / Remote	ON (down): Remote					
SW1 - 7	50Hz / 60Hz	ON (down): 60Hz					
SW1 rest	Not used						

#### **POWER DERATING VS AMBIENT TEMP.**



#### **DESCRIPTION**

The ODX-6000 consists of three phase sine-wave DC-AC inverters with galvanic isolation between input and output.

The unit allows:

- Changing the output frequency by means of DIP-switch-7 of SW1. OFF: 50Hz or default programmed, ON: 60Hz
- Change local/remote (waiting RS-232 commands) by means of DIP-switch-6 of SW1. OFF: local, ON: remote
- Shutdown applying voltage output 15 to 143V on pins 3 and 4 of J4
- Start-up motors by means of a soft start. In the start-up, the output voltage rises linearly from 0V to set voltage and the frequency from the initial to the set one. The startup ramp slope may be changed via RS-232
- Set the rotation speed of a motor according to the appropriate Voltage/Frequency ratio.
- Configurable input (pin 1 and 2 of J4):
  - Reverse mode: Changing the rotation direction for the next start-up of a motor by applying voltage between 15 and 143V.
  - Mid power mode: Changing the output frequency in V/F mode from nominal to a mid-power frequency by applying voltage between 15 and 143V.
- Monitoring the status of the input and output voltage through the contacts of two separate solid state relays.
- Set and monitor parameters via RS-232.

The ODX-6000 is equipped with a maximum average power protection as well as maximum output peak current protection. This protects the semiconductors even when an output short-circuit occurs. It also features a disable function for input under-voltage, which allows protecting the batteries from harmful discharges.

#### **START-UP**

- The unit has 6 threaded holes for the fixation on a mounting surface.
- The unit has internal fans. For an appropriate cooling, the air input and output should be free of elements that cause and an air flow reduction (minimum recommended distance to other objects 90mm).
- · Make connections as shown in the figure.
- The default output frequency is 50Hz. For 60Hz simply actuate the dip-switch as indicated in the figure.

## For safety reasons, the following requirements must be met:

- Provide the equipment with some kind of protective enclosure that complies with the electrical safety directives in effect within the country where the equipment is installed.
- Include an input fuse with a rating immediately higher than the maximum input current.
- Use cables of adequate cross-section to connect inputs and outputs. The following table lists the maximum currents and the minimum cross-sections for the cables used for each power connection.

	Input	Input	Input	Input	Output
	24V	48V	72V	110V	400V
Maximum current	232 A	191 A	127A	83A	8.7A
Cable cross-section	150	95	50	25	2.5
	mm <sup>2</sup>	mm²	mm²	mm²	mm <sup>2</sup>

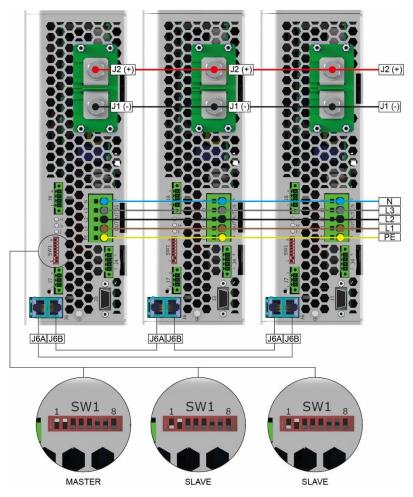


#### **PARALLEL OPERATION**

The models 75xxTPN are designed to work in parallel with one unit set as a MASTER and the rest as SLAVES.

For this mode of operation, it is necessary to connect the MASTER/SLAVE port with a cable RJ45 FTP cat 6 (or higher) from J6B of the first unit to J6A of the following, and the last unit J6B to J6A of the first unit in a ring connection.

In addition, it is necessary to interconnect the output port respecting the phase order, as shown in the diagram:



Example for 3 units working in parallel mode

#### **STAND ALONE OPERATION**

The models 75xxTPN, can operate stand alone with no connections, setting the dip-switch SW1-1 OFF (MASTER), and SW1-2 ON (Alone) as the diagram show:





#### **RS232** communication port

It is possible to control and monitor de unit via RS232 by means of an application tool named PAM. This application is free and can be downloaded from the Premium website

Also it is possible to control and monitor de unit directly using the protocol showed in table:

Protocol configuration: ASCII code, 57600 bauds, parity none, 8 bits, 1bit stop

Hea	ader	Function	Para	meter	Returns	Explanation
				V	PTV∎∎∎.∎	Input voltage in Volts
			,	v	PTv===.=	Input voltage ripple in Volts
			Y		PTYRN===== [13]YSN===== [13]YTN=====	Output voltage in Volts RMS Phase-Neutral ([13] = char 13 of ASCII code)
				I	PTIR===.==[13]IS===.== [13]IT===.==	Output current in Amps RMS ([13] = char 13 of ASCII code)
				Т	PTT===.=	Internal temperature1 in K
				t	PTt===.=	Internal temperature 2 in K
				F	PTF===.=	Nominal output frequency in Hz
		L	f		PTf∎≡∎.≡	Actual output frequency in Hz
				у	PTy∎∎∎.∎	Actual output voltage set-point in V
			S		PTS■■■.■	Inverter state  999.9 → Enabled  000.0 → Disabled  222.2 → Blocked by overload  111.1 → Blocked by overload or shortcircuit
			ı	M	PTM===	Model number
			R		PTR∎∎∎	Firmware version
			Ot	her	PTE	Command not supported
			1	===.=	OK / ERR	Set the low input voltage timed shutdown in V
			2	===.=	OK / ERR	Set the minimum alarm input voltage in V
			3	===.=	OK / ERR	Change the status bit (after start up enabled with SW1:6 =LOCAL and disabled with SW1:6 =REMOTE)  999.9 → Inverter enabled  000.0 → Inverter disabled
			4	===.=	OK / ERR	Set the output voltage Phase-neutral in Vrms (Vo)(output must be stopped) 040.0≤ ■■■.■ ≤ 230.0
Р	R		5		OK / ERR	Set the maximum output current in Arms 20% I <sub>nom</sub> ≤ ■■■.■ ≤ 100% I <sub>nom</sub>
			6	===.=	OK / ERR	Set the nominal output frequency in Hz (Fo) (output must be stopped) 005.0 ≤ ■■■.■ ≤ 075.0
		G	7	===.=	OK / ERR	Set the alarm maximum output current  0 < ■■■.■ ≤ 100% I <sub>max_warning</sub>
			8	===.=	OK / ERR	111.1 → Reset the inverter
			L	===.=	OK / ERR	Set the minimum input starting voltage in Volts
			0	===.=	OK / ERR	Set the initial frequency in the startup (Fi) 005.0 ≤ ■■■.■ ≤ 075.0
			Р	===.=	OK / ERR	Set the ramp-up in increment of "N" cycles per Hz in mode V/F, frequency changes or start-up (Note-1) 001.0 ≤ ■■■.■ ≤ 100.0
			Q	===.=	OK / ERR	Set the ramp-down in decrement of "N" cycles per Hz in mode V/F (Note-1) 002.0 ≤ ■■■.■ ≤ 100.0
			Y		OK / ERR	Change the working mode of the input J4-1,J4-2  111.1 → Input as reverse phase control (default)  222.2 → Input as mid-power control (Note-2)
			X		OK / ERR	Set the mid-power frequency for V/F mode by the use of input J4-1,J4-2 005.0 ≤ ■■■.■ ≤ 75.0
			1		OK / ERR	Set a new output frequency in Hz (output must be run and not stored in memory) 005.0 ≤ ■■■.■ ≤ 075.0
			2		OK / ERR	Set a new output voltage in Volts (output must be run and not stored in memory) 040.0 ≤ ■■■.■ ≤ 230.0
	M	M			OK / ERR	Set a new output frequency in Hz in mode V/F (output must be run and not stored in memory) 005.0 ≤ ■■■.■ ≤ 075.0
		4		OK / ERR	Changes the output phase order (output must be run and not stored in memory)  111.1 → Phase RST (direct phase)  222.2 → Phase SRT (reverse phase)	

#### **CAN** communication port (optional)

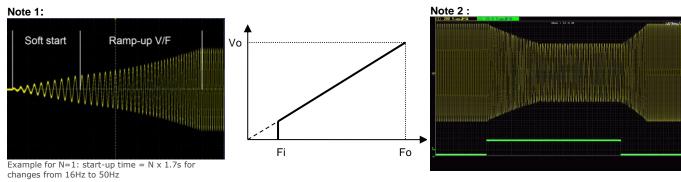
It is possible to control and monitor the unit using the CAN connection with the CANOpen protocol. It is provided an .eds file with all the objects available.

**Protocol configuration:** 250kbit/s, NODE ID: 1. The most relevant objects can be found in the following table:



Index	Subindex	Name	Type	Attribute	Explanation
0x6001	0x00	Input voltage	UINT32	ro	Input voltage in tenths of Volt
0x6002	0x00	Input Ripple Voltage	UINT32	ro	Input voltage ripple in tenths of Volt
0x6003	0x01	Vrn	UINT32	ro	Output voltage in Volts Phase R-Neutral
0x6003	0x02	Vsn	UINT32	ro	Output voltage in Volts Phase S-Neutral
0x6003	0x02	Vtn	UINT32	ro	Output voltage in Volts Phase T-Neutral
0x6004	0x01	IR	UINT32	ro	Output current in hundredths of Amp Phase R
0x6004	0x02	IS	UINT32	ro	Output current in hundredths of Amp Phase S
0x6004	0x03	IT	UINT32	ro	Output current in hundredths of Amp Phase T
0x6005	0x00	Internal temperature Secondary	UINT32	ro	Internal temperature1 in tenths of K
0x6006	0x00	Internal temperature Primary	UINT32	ro	Internal temperature 2 in tenths of K
0x6007	0x00	Nominal output frequency	UINT32	ro	Nominal output frequency in Hz
0x6008	0x00	Actual output frequency	UINT32	ro	Actual output frequency in Hz
0x6009	0x00	Actual output voltage set-point	UINT32	ro	Actual output voltage set-point in V
0x600A	0x00	Inverter state	UINT16	ro	$\begin{split} &\text{Inverter state} \\ &3 \rightarrow \text{Enabled} \\ &\textbf{0} \rightarrow \text{Disabled} \\ &\textbf{2} \rightarrow \text{Blocked by overload} \\ &\textbf{1} \rightarrow \text{Blocked by overload or shortcircuit} \end{split}$
0x600B	0x00	Product ID	UINT16	ro	Model number
0x600C	0x00	Firmware version	UINT16	ro	Firmware version
0x6100	0x00	Low input voltage timed shutdown	UINT32	rw	Set the low input voltage timed shutdown in tenths of V
0x610B	0x00	Input voltage minimum warning	UINT32	rw	Set the minimum alarm input voltage in tenths of V
0x6101	0x00	AC status bit	UINT8	rw	Change the status bit (after start up enabled with SW3 =LOCAL and disabled with SW3 =REMOTE)  1 → Inverter enabled  0 → Inverter disabled
0x6102	0x00	Nominal output voltage	UINT32	rw	Set the output voltage Phase-neutral in Vrms (Vo) (output must be stopped) $40 \le X \le 230$
0x6103	0x00	Maximum output current	UINT32	rw	Set the maximum output current in Arms (per mille) 200‰ I <sub>nom</sub> ≤ ■■■■ ≤ 1000‰ I <sub>nom</sub>
0x6104	0x00	Nominal frequency	UINT32	rw	Set the nominal output frequency in Hz (Fo) (output must be stopped) $5 \le x \le 75$
0x6105	0x00	Alarm maximum output current	UIN32	rw	Set the alarm maximum output current in Arms (per mille) 0% ≤ x ≤ 1000‰ I <sub>max_warning</sub>
0x6106	0x00	Inverter reset	UINT8	wo	1 → Reset the inverter
0x6107	0x00	Minimum starting input voltage	UINT32	rw	Set the minimum input starting voltage in tenths of Volts
0x6108	0x00	Start frequency	UINT32	rw	Set the initial frequency in the startup (Fi) $5 \le x \le 75$
0x6109	0x00	Ramp up value	UINT32	rw	Set the ramp-up in increment of "N" cycles per Hz in mode V/F, frequency changes or start-up (Note-1) $1 \le x \le 100$
0x610A	0x00	Ramp down value	UINT32	rw	Set the ramp-down in decrement of "N" cycles per Hz in mode V/F (Note-1) $2 \le x \le 100$
0x6120	0x00	confi_inversion	UINT8	rw	Change the working mode of the input J4-1,J4-2  0 → Input as reverse phase control (default)  1 → Input as mid-power control (Note-2)
0x6121	0x00	Mid_power _frequency	UINT32	rw	Set the mid-power frequency for V/F mode by the use of input J4-1,J4-2 $5 \le x \le 75$
0x6200	0x00	Runtime target frequency	UINT32	wo	Set a new output frequency in Hz (output must be run and not stored in memory) $5 \le x \le 75$
0x6201	0x00	Runtime output voltage	UINT32	wo	Set a new output voltage in Volts (output must be run and not stored in memory) $40 \le x \le 230$
0x6202	0x00	Runtime frequency V/F	UINT32	wo	Set a new output frequency in Hz in mode V/F (output must be run and not stored in memory)  5 ≤ ■■■■ ≤ 75
0x6203	0x00	Change phase order	UINT32	wo	Changes the output phase order (output must be run and not stored in memory)  1 → Phase RST (direct phase)  2 → Phase SRT (reverse phase)





Mode V/F curve

Example for change from 50Hz / 400V to 30HZ and 240V with ramp-down of 2 cycles /Hz and ramp-up de 1 Cycle/Hz. Yellow: output voltage and Green: Mid-Power input signal

#### **WORKING PARAMETERS**

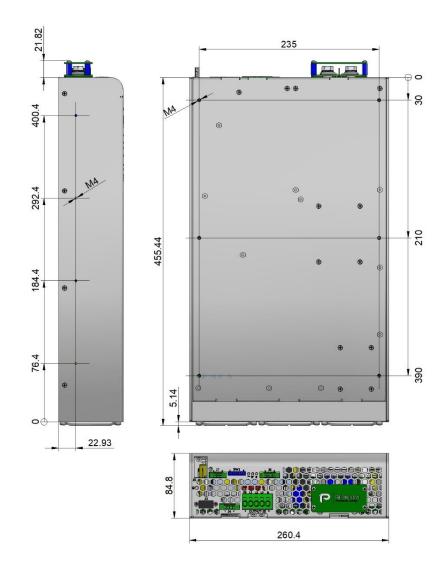
Thermal protection					
Internal warning temperature (output alarm) 88					
Internal shutdown temperature 92					
Internal restart temperature		7	5		°C
Internal temperature of fan start-up		4	5		°C
Input voltage parameters	24V	48V	72V	110V	
High input voltage shutdown instantaneous	33.6	62.4	93.6	143.0	Vdc
High input voltage timed shutdown (t) (Input alarm)	31.2	60.0	90.0	137.5	Vdc
Start-up voltage	19.2	38.4	57.6	88.0	Vdc
Low input voltage timed shutdown (t) (Input alarm)	16.8	33.6	50.4	77.0	Vdc
Low input voltage instantaneous shutdown	14.4	28.8	43.2	66.0	Vdc
Time to shutdown (t)		50	00		ms
Output voltage parameters					
Output voltage phase-neutral		23	30		Vac
Output under-voltage shutdown		< 85% of set	ting 1000ms		
Warning voltage (output alarm)		< 90% of se	tting 200ms		
Initial start-up frequency		Į.	5		Hz
Soft start duration		1 cy	cles		
Ramp-up V/F		1 Hz/	cycle		
Output current parameters					
Maximum continuous output current	6.52	8.66	8.66	8.66	А
Warning current (output alarm)	6.20	8.22	8.22	8.22	А
Maximum overload I <sup>2</sup> t		See figu	re below		
Time between restart attempts		40	00		ms
Number of attempts of consecutive overload		į.	5		
Working failures and reset					
Lock for continuous overload or internal failure		Unlimit	ed time		
Reset time by input disconnection		>	2		min

Configurable parameters underlined

#### **OVERLOAD PROTECTION**

Protection against overloads and short-circuits	By <b>current</b> limiting at Iopk By <b>I<sup>2</sup>t</b> . The unit shutdowns when the current-time is over the continuous operation curve	1000s 100s	Shutdown Current Limit (lopk)
Overload protection recovery	Every 4 seconds after shutdown, the unit tries to restart up to 5 times. If the overload persists, the unit reminds shutdown until an <b>input reconnection</b> .	10s 1s	Continuous Operation  05 115 130 145 160 175 190 205% Ionom

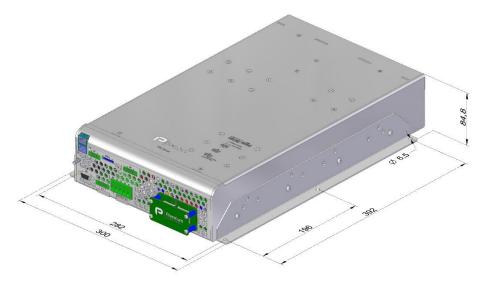




**NOTE**: All the fixing holes are M4. Maximum screw length inside de inverter 5mm.

#### **ACCESSORIES**

Description	Notes	CODE
Mounting brackets kit	Contains two brackets and screws	NP-9282





## **CE** EU, UKCA DECLARATION OF CONFORMITY

The undersigned, representing the following:

Manufacturer: PREMIUM, S. A.,

Address: C/ Dolors Aleu 19-21, 08908 L'Hospitalet de Llobregat, SPAIN

herewith declares that the product:

Type: DC/DC converter

Models: **ODX-6000-7502 ... 7507** 

is in conformity with the provisions of the following EU directive(s):

2014/35/EU SI 2016 No 1101 Low voltage / The electrical equipment (safety) regulations

2014/30/EU

SI 2016 No 1091 EMC / Electromagnetic compatibility regulations

2015/863/EU RoHS / Restriction of the use of certain hazardous substances in electrical and

SI 2012 No. 3032 electronic equipment

and that standards and/or technical specifications referenced below have been applied:

EN 60950-1: 2005 Safety. Information technology equipment

EN 62368-1: 2014 Safety. Audio/video, information and communication technology equipment

EN 61000-6-3: 2007 Generic emission standard
EN 61000-6-2: 2005 Generic immunity standard

EN 50155: 2017\* Railway applications. Electronic equipment used on rolling stock material

EN 50121-3-2: 2016\* Railway applications. EMC Rolling stock equipment

CE marking year: 2019; UKCA marking year: 2021

#### Notes:

For the fulfilment of this declaration the product must be used only for the aim that has been conceived, considering the limitations established in the instructions manual or datasheet.

L'Hospitalet de Llobregat, 13-09-2021

Albert Sole Technical Director

**PREMIUM S.A.** is an ISO9001and ISO14001 certified company by**Bureau Veritas** 

<sup>\*</sup> Optional, See annexe



#### **ANNEXE**

4.3.1	Working altitude	Up to 2000m									
4.3.1	Working aititude		and Tr	Class OT1	(-25 t	55 °C)	V. load	< 100 %			
4.3.2	Ambient temperature	For options B a For options B a For option L: Cl For option L: Cl	For options B and T: Class OT1 (-25 to 55 °C): load < 100 % For options B and T: Class OT3 (-25 to 70 °C): load <62.5 % For options B and T: Class OT5 (-25 to 85 °C): load <25 % For option L: Class OT2 (-40 to 55 °C): load < 100 % For option L: Class OT4 (-40 to 70 °C): load <62.5 % For option L: Class OT6 (-40 to 85 °C): load <25 %								
1.3.3	Switch-on extended operating temp.	ST1	·								
1.3.4	Rapid temperature variations	H1									
1.3.5	Shocks and vibrations	According EN61	1373:2	010 Cate	gory 1	class B					
						_					
		Test	N	lorm	Por			uency	Limits		
		Dedisted						230MHz	40dB(μV/m) Qpk at 10m		
		Radiated	IEC	55016	Cas	e		Iz1GHz	47dB(μV/m) Qpk at 10m Do not apply		
		emissions						3GHz 6GHz	Internal freq. < 108MHz		
		Conducted						500kHz	99dB(μV) Qpk		
		emissions	IEC	55016	Inpu			z30MHz	93dB(µV) Qpk		
		000.00				I I	3001111	5011112	3305(µ*) Qpi		
		Test		Norn	n	Po	rt	Severity	Conditions	1	
		Electrostation		IEC61000	)-4-2	Cas	se	±8kV	Air (isolated parts)	- 1	
	EMC Electromagnetic	discharge						±8kV 20V/m	Contact (conductive parts) 0.081.0GHz M. 80% 1kHz	+	
	Compatibility	Radiated high-frequency						10V/m	1.42.1GHz M. 80% 1kHz	-	
.3.6	Compacibility			IEC61000-4-3		X/Y/Z	Axis		2.12.5GHz M. 80% 1kHz	-	
	EN50121-3-2:2016	mgn nequen	10,					3V/m	5.16Ghz M. 80% 1kHz		
		Fast transients		ts IEC61000-4-4		Inp	ut	±2kV			
						Output		±2kV	Tr/Th: E/E0 no		
		rast transien	its	1201000-4-4		Sigr		±2kV	Tr/Th: 5/50 ns		
						PE		±1kV			
		Surge				Input l		±1kV	Tr/Th: 1.2/50µs		
				12001000 . 0		Input L to PE Input		±2kV	Π/ Π. 1.2/ 30μ3		
		Conducted RF		onducted RF IEC61000-4-6		Output		10V 10V			
							6 Signal		0.1580MHz M. 80% 1kHz		
						PE		10V			
		Magnetic fie	eld				300A/m	0Hz, 16.7Hz, 50/60Hz			
		P= Performance criteria, L= Line, PE= Protective Earth									
1.3.7 5.1.1.2	Relative humidity DC power supply range	Up to 95% From 0.70 to 1			us						
.1.1.3	Temporary DC power supply fluctuation	From 0.60 to 1 From 1.25 to 1			ut dam	age					
.1.1.4	Interruptions of voltage supply	Class S1 (witho	out inte	erruptions	s)						
5.1.1.6	Input ripple factor Supply change-over	10% peak to pe 0.6 Un duration						ormance crit	erion A		
.2.7	Input reverse polarity protection	By external fus									
.0.7	Protective coating for PCB assemblies	Class PC2									
13.3	Tests list	1 Visual Inspection 2 Performance test 3 Power supply test 4 Insulation test 5 Low temperature storage test 6 Low temperature start-up test 7 Dry heat test 8 Cyclic damp heat test 9 Salt mist test 10 Enclosure protection test (IP code) 11 EMC test 12 Shocks and vibrations test 13 Equipment stress screening test					R R R T T T - - T	outine outine outine outine ype ype ype ype ype	at 40°C and load 100%		